



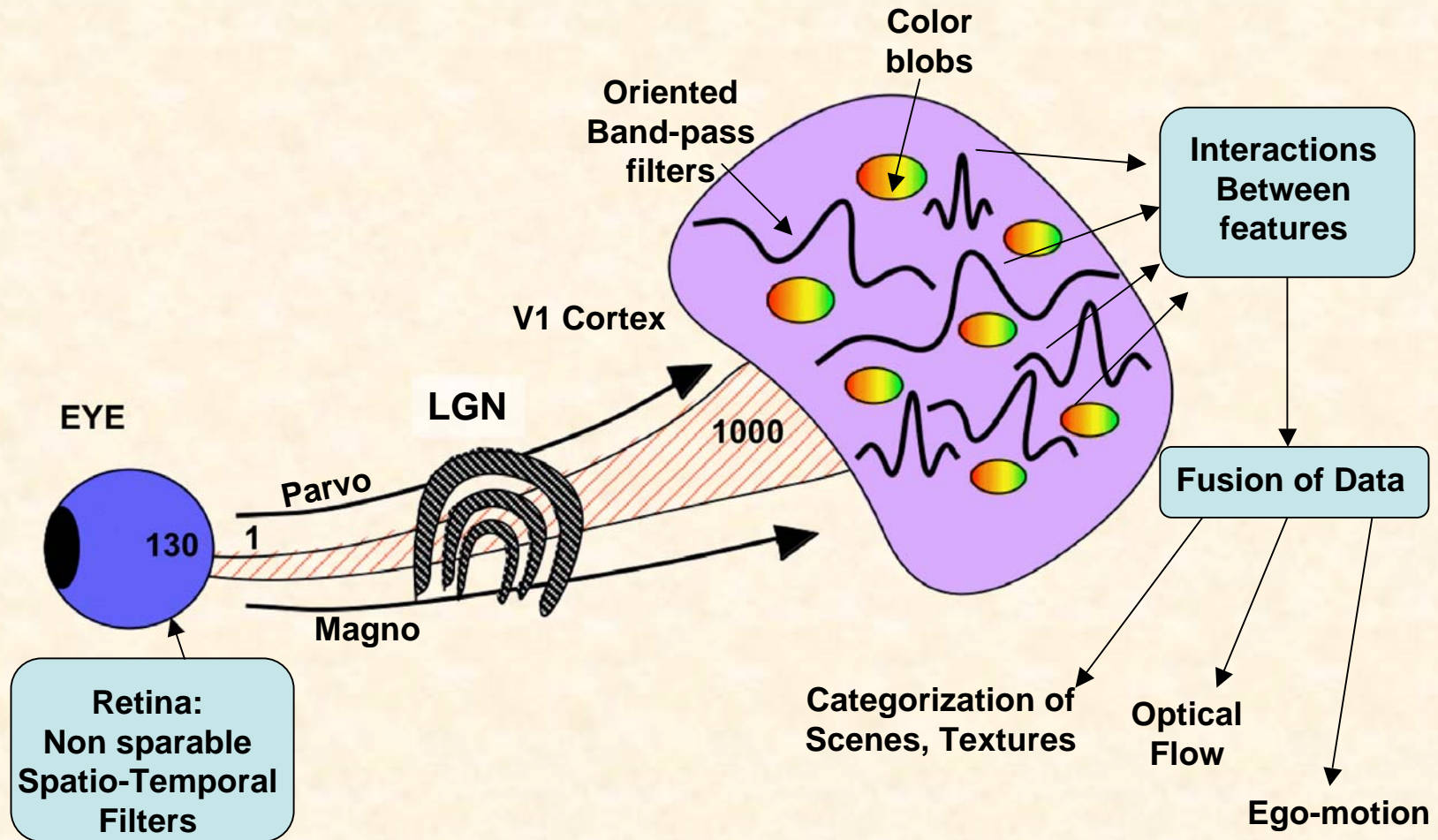
The Visual System: Reducing Variability to Better Categorize

Jeanny Herault

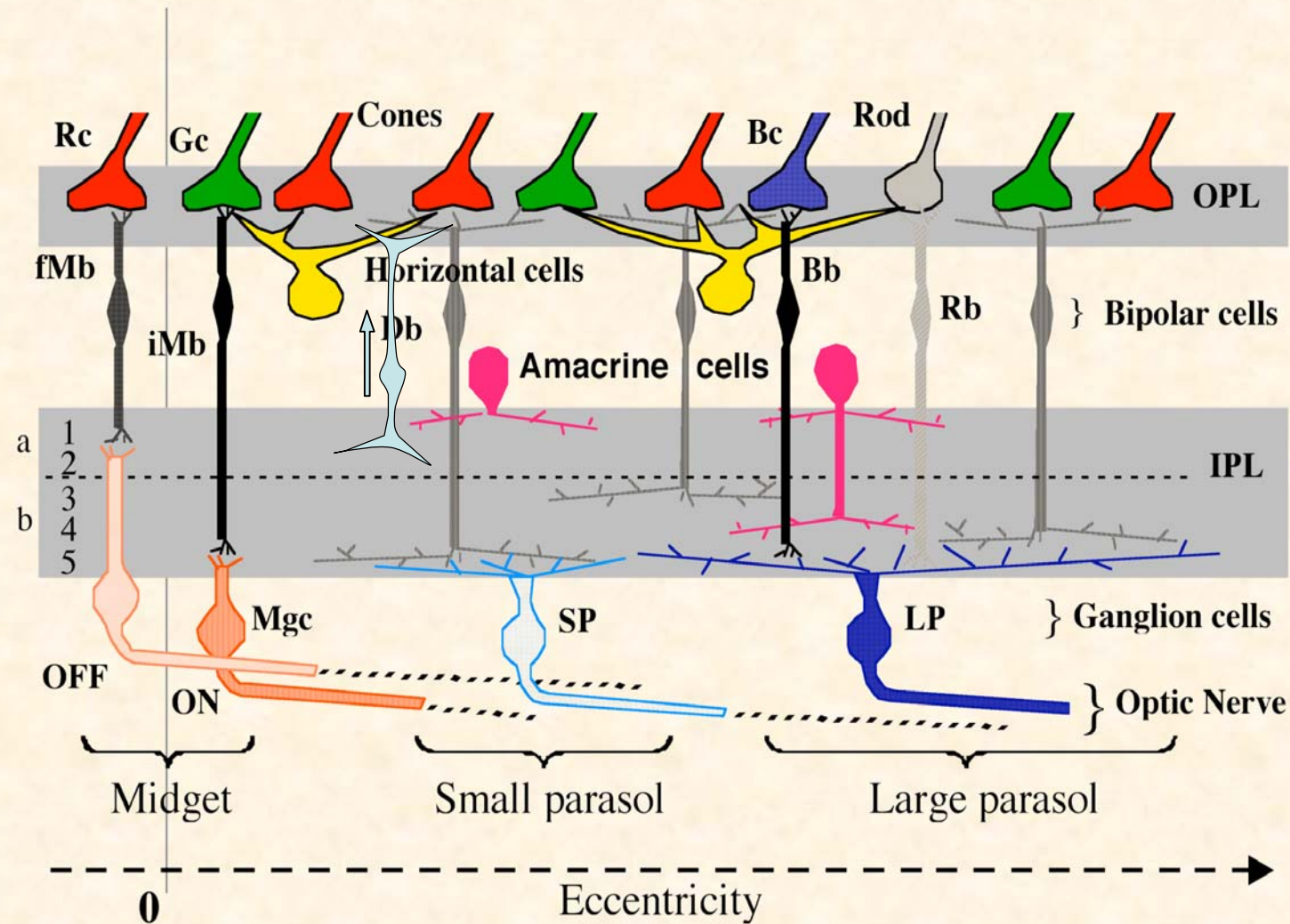
GIPSA-lab, Dept. Images & Signal,
Perception team, Grenoble

STATIM - Paris - January 2009

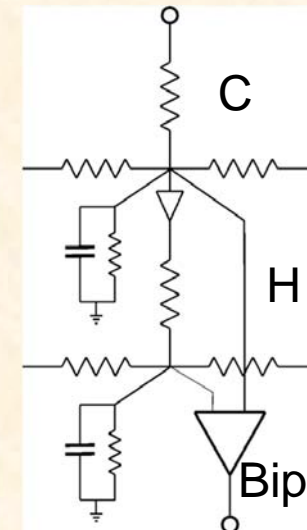
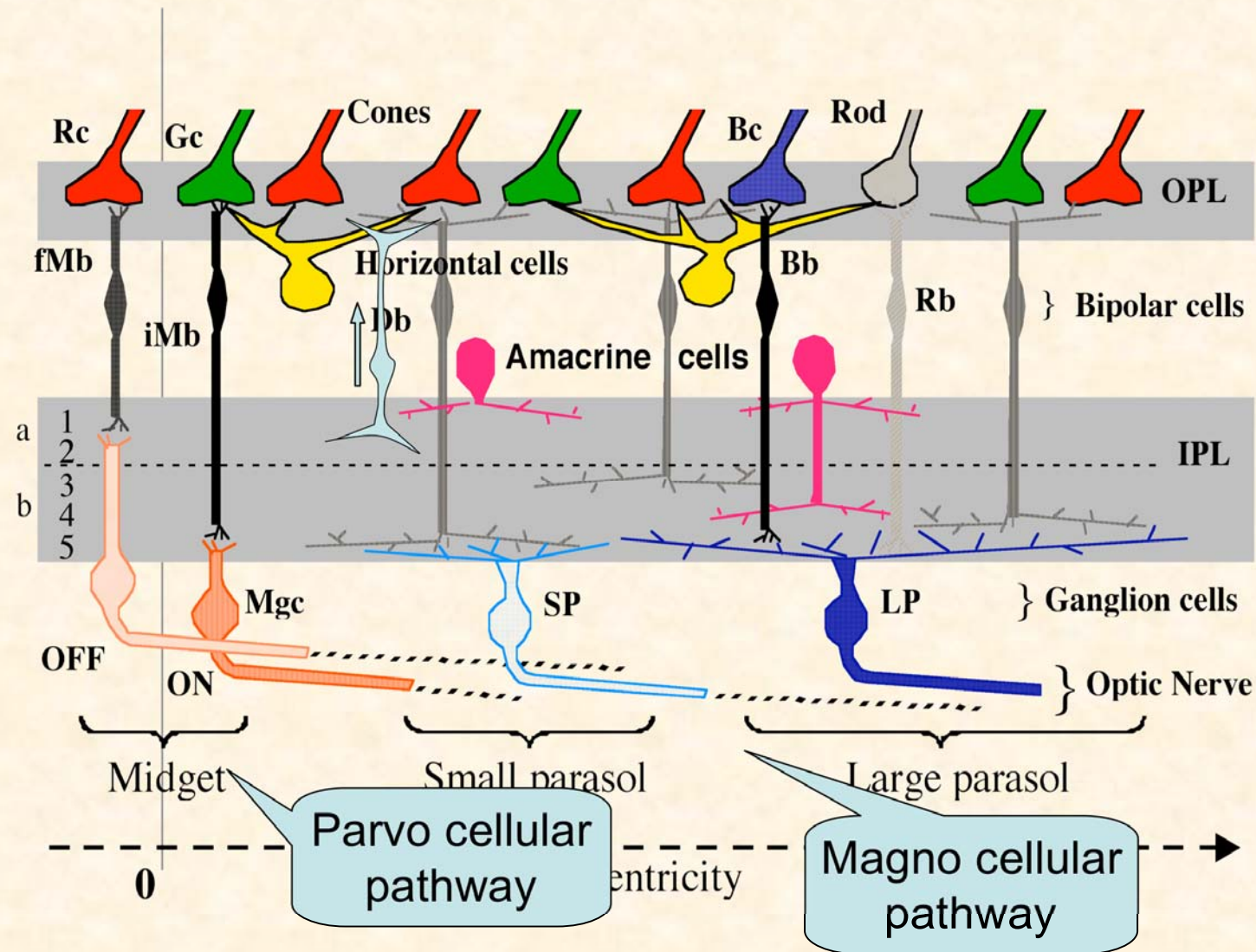
Visual System: Anatomy



Retina: Linear Model (basics)



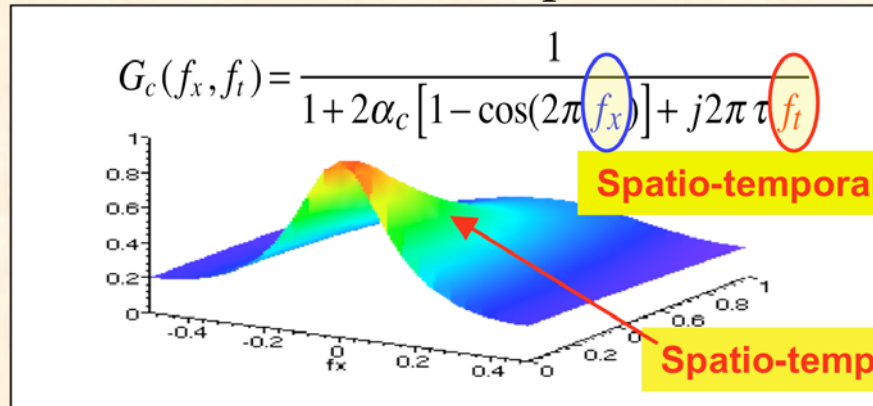
Retina: Linear Model (basics)



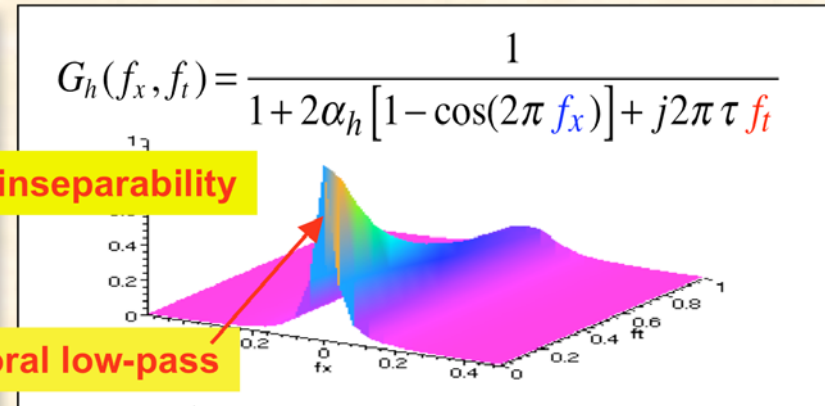
Retina: Parvo Cellular Pathway

Transfer function (properties)

Photoreceptors

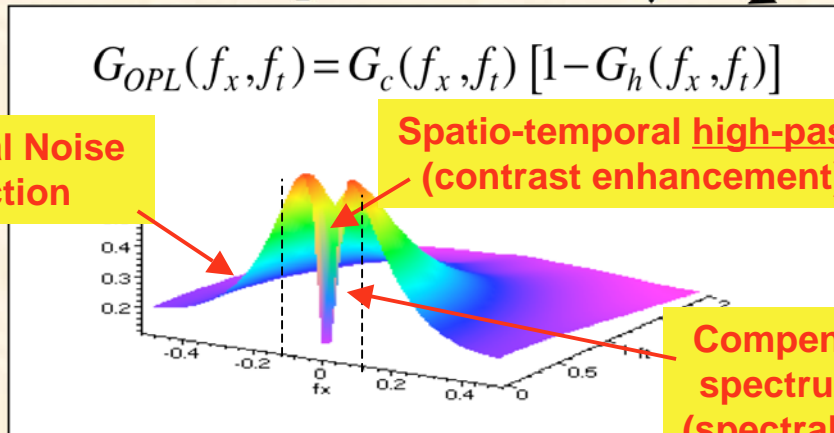


Horizontal cells

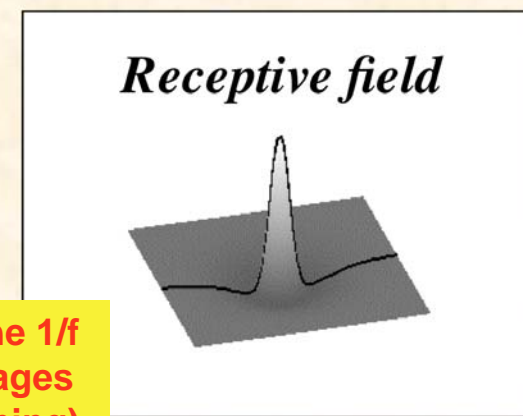


Bipolar cells :

+ -

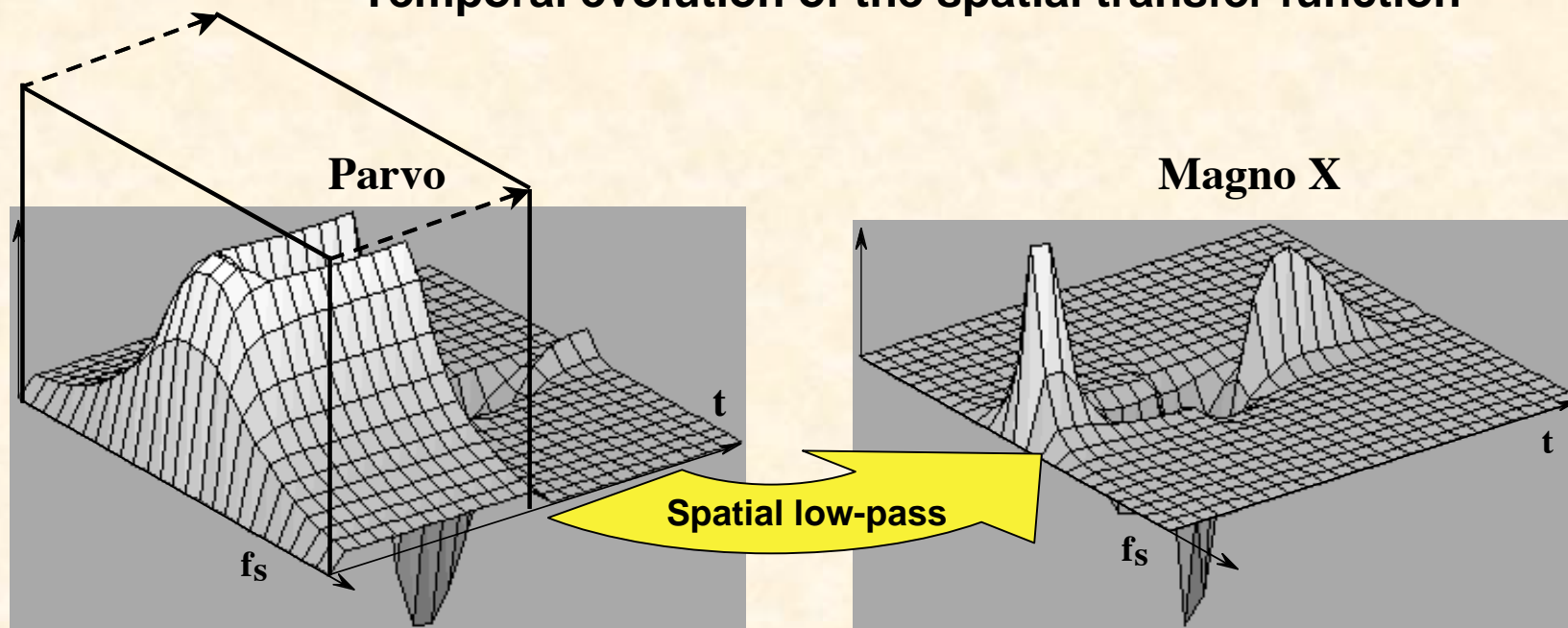


Receptive field



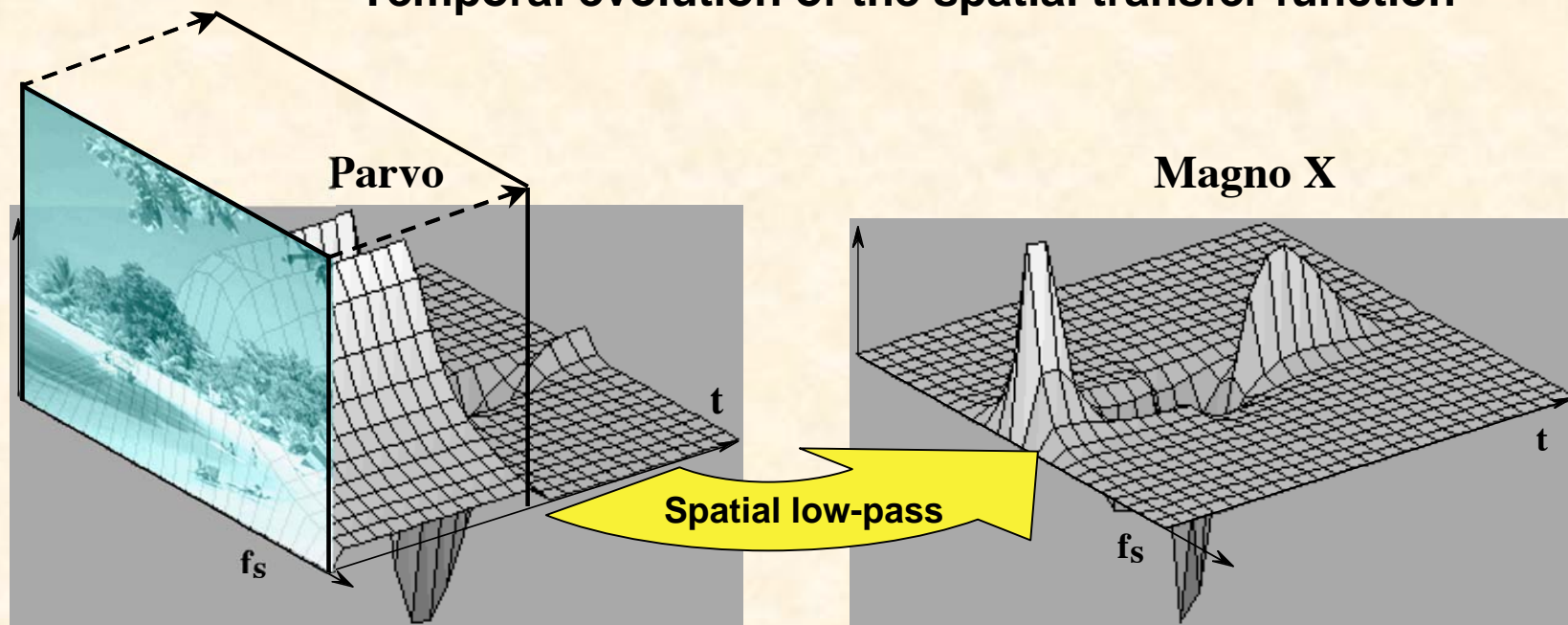
Parvo- & Magnocellular Pathways

- Temporal evolution of the spatial transfer function



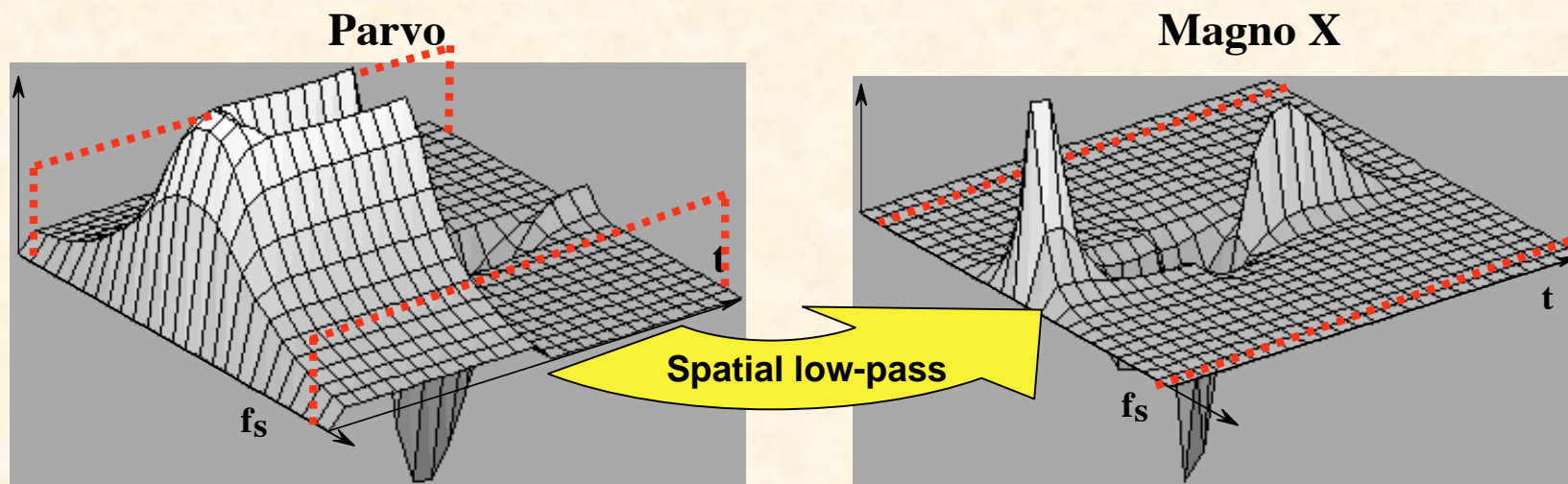
Parvo- & Magnocellular Pathways

- Temporal evolution of the spatial transfer function

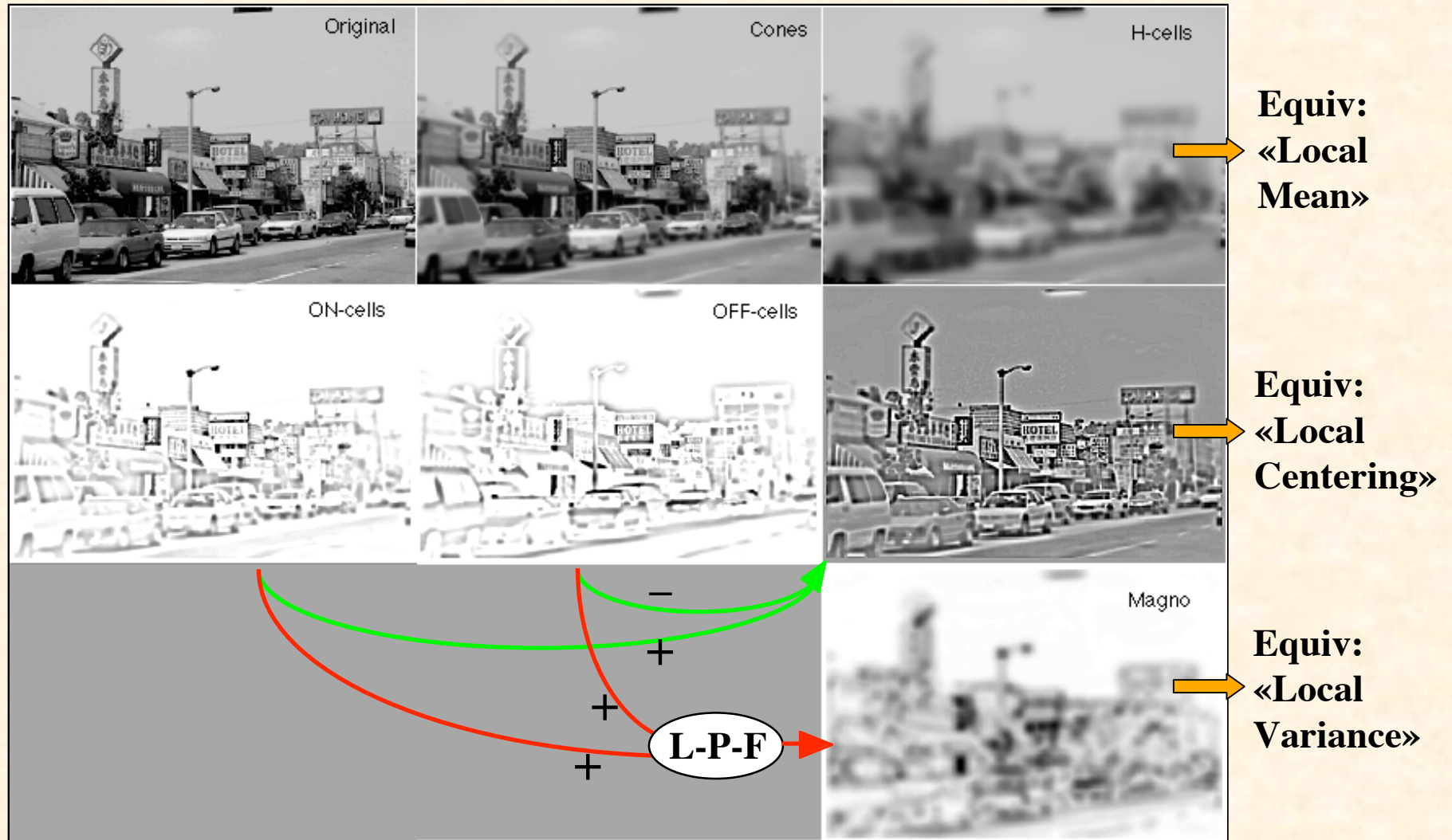


Parvo- & Magnocellular Pathways

- Temporal evolution of the spatial transfer function

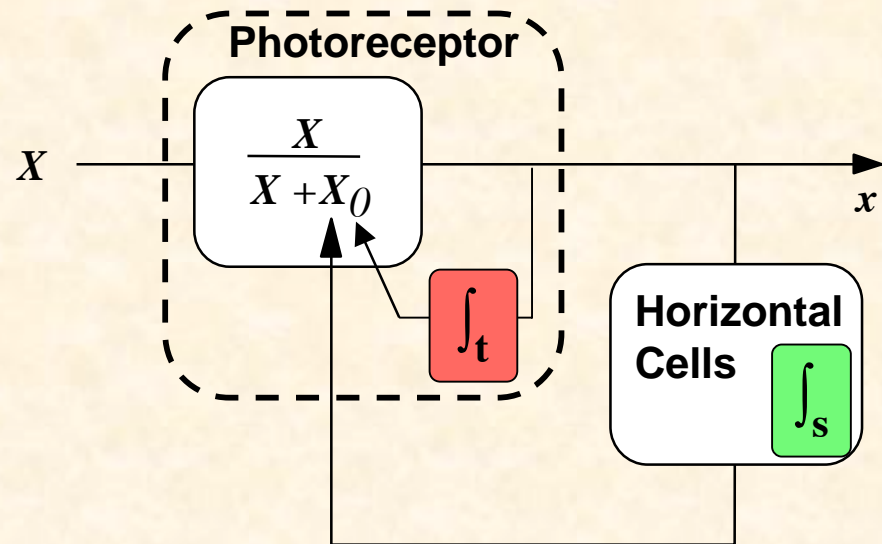


Retina: Summary

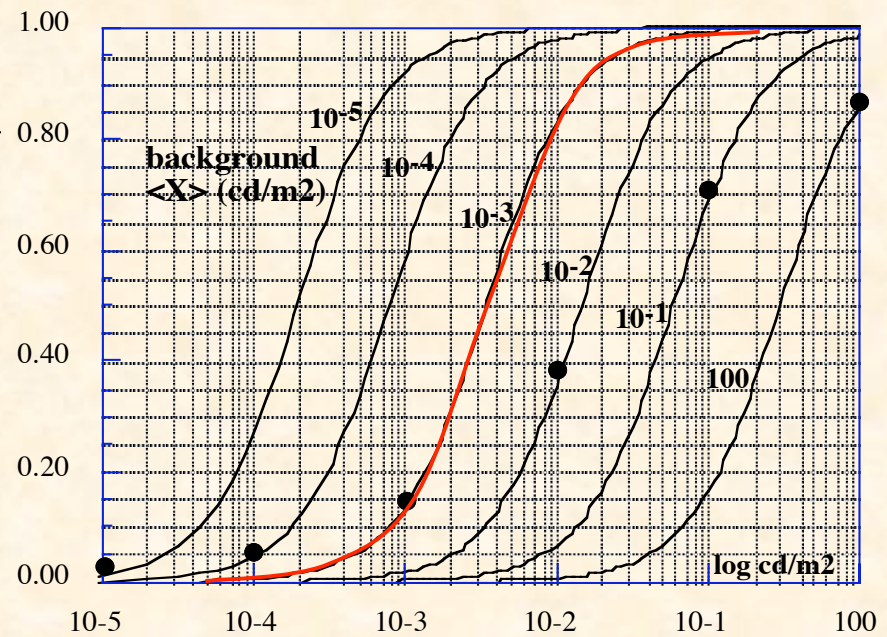


Retina: Non-Linearities

1. Photoreceptors' adaptive compression



$X_0 =$ Temporal
 \Rightarrow and
spatial Mean



Retina: Non-Linearities

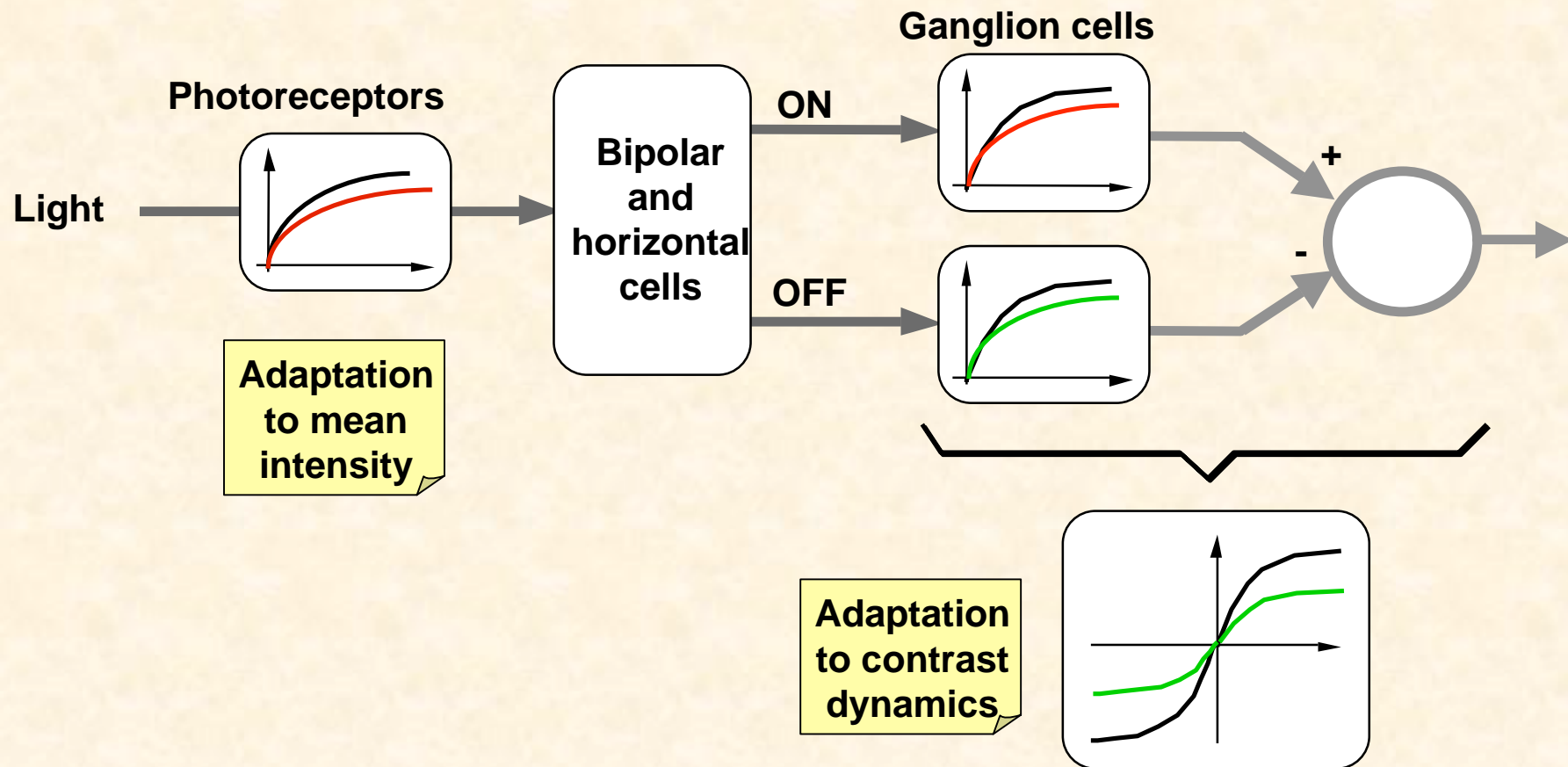
1. Photoreceptors' adaptive compression: application



More
details in
Shadows

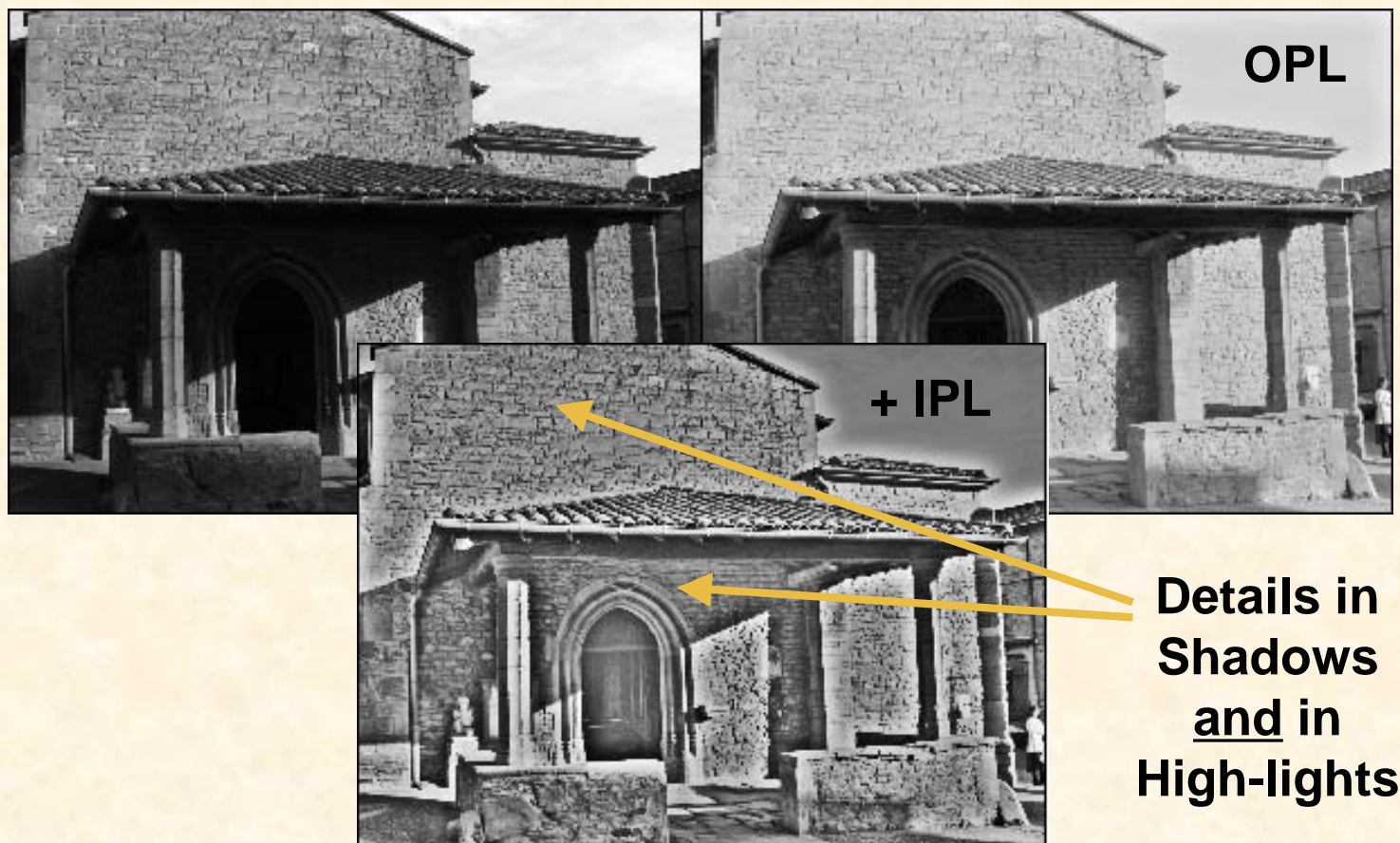
Retina: Non-Linearities

2. Compressive Adaptation in IPL



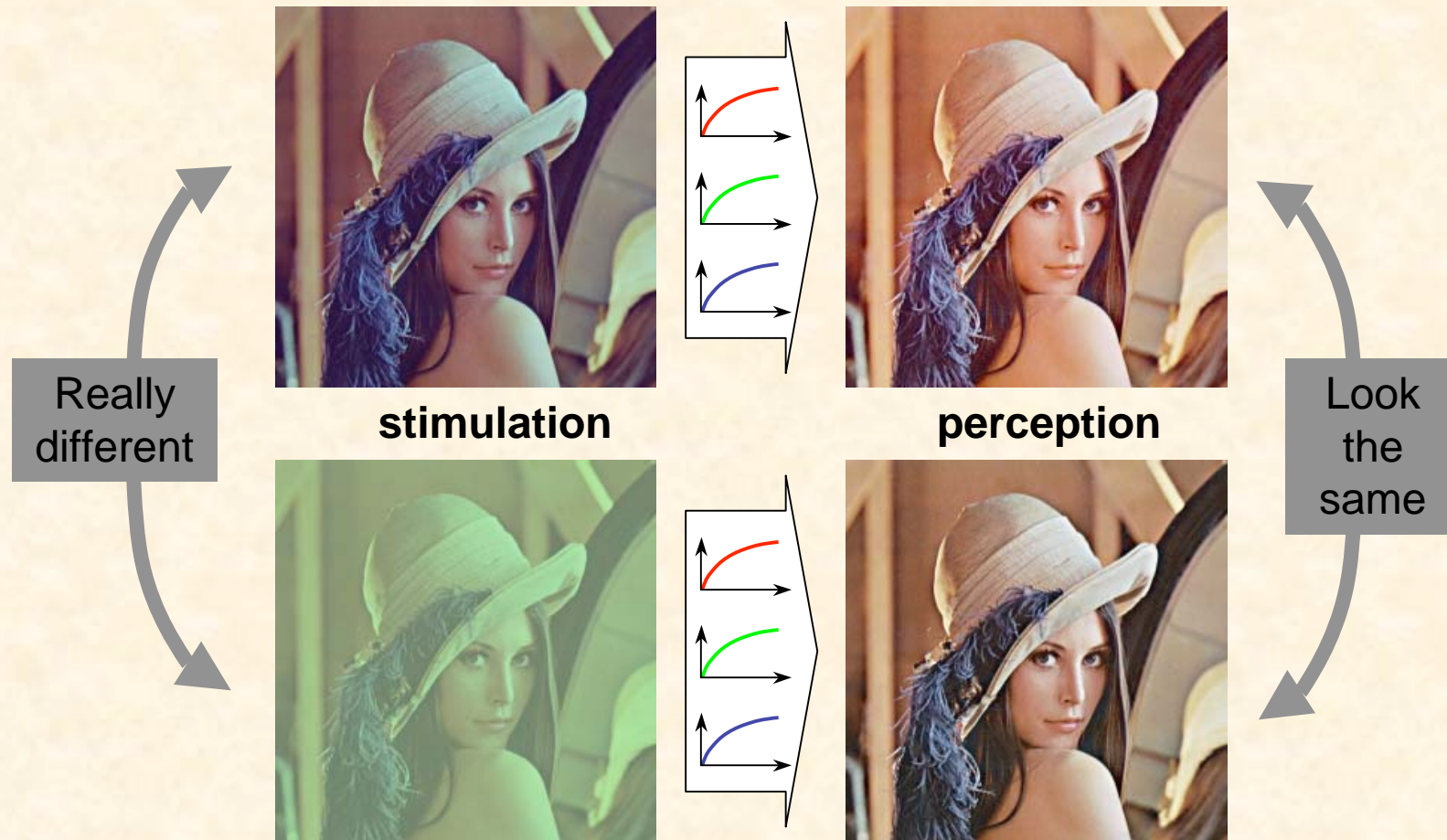
Retina: Non-Linearities

2. Compressive Adaptation in IPL: application

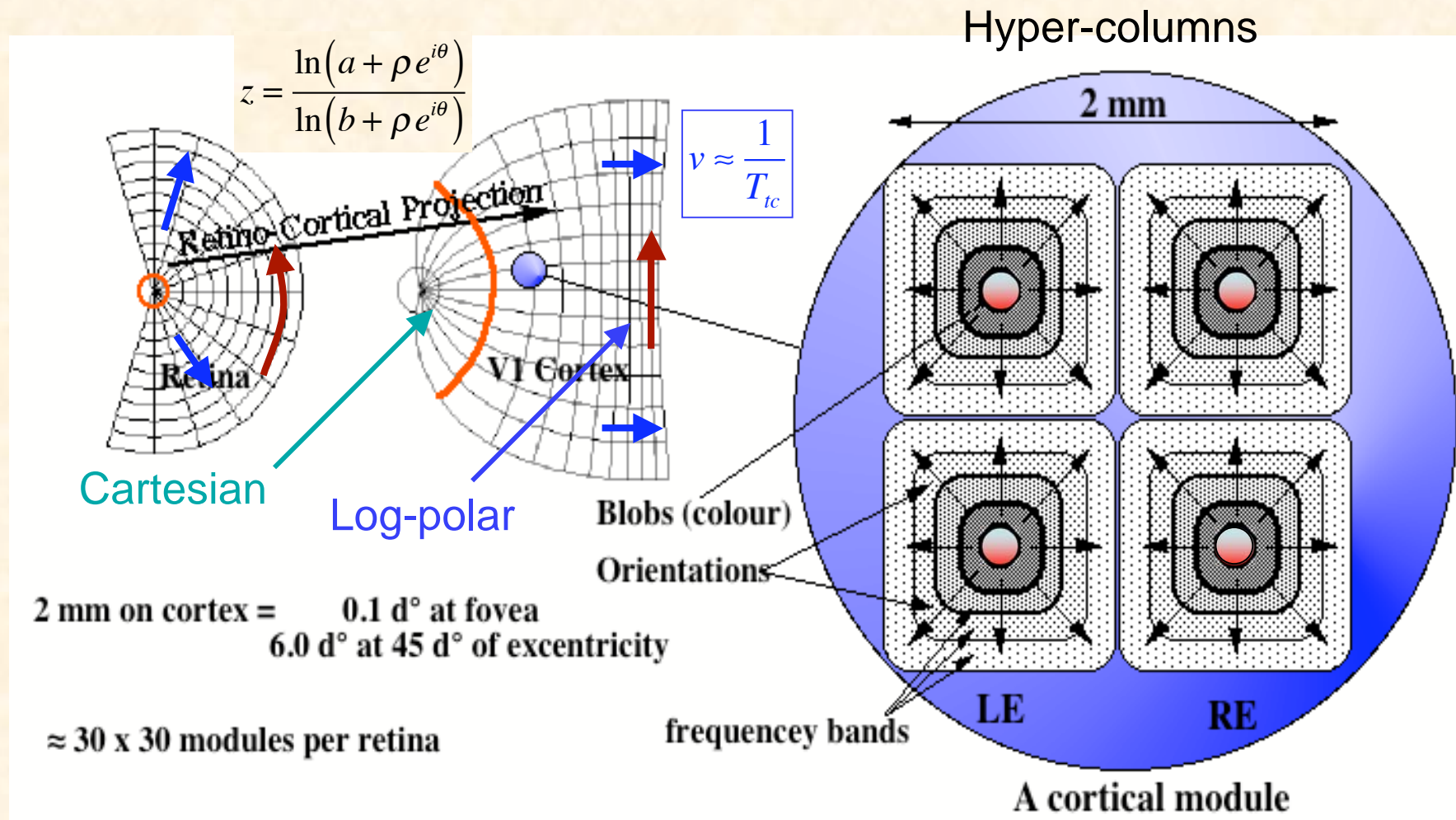


Non-Linearity and Color

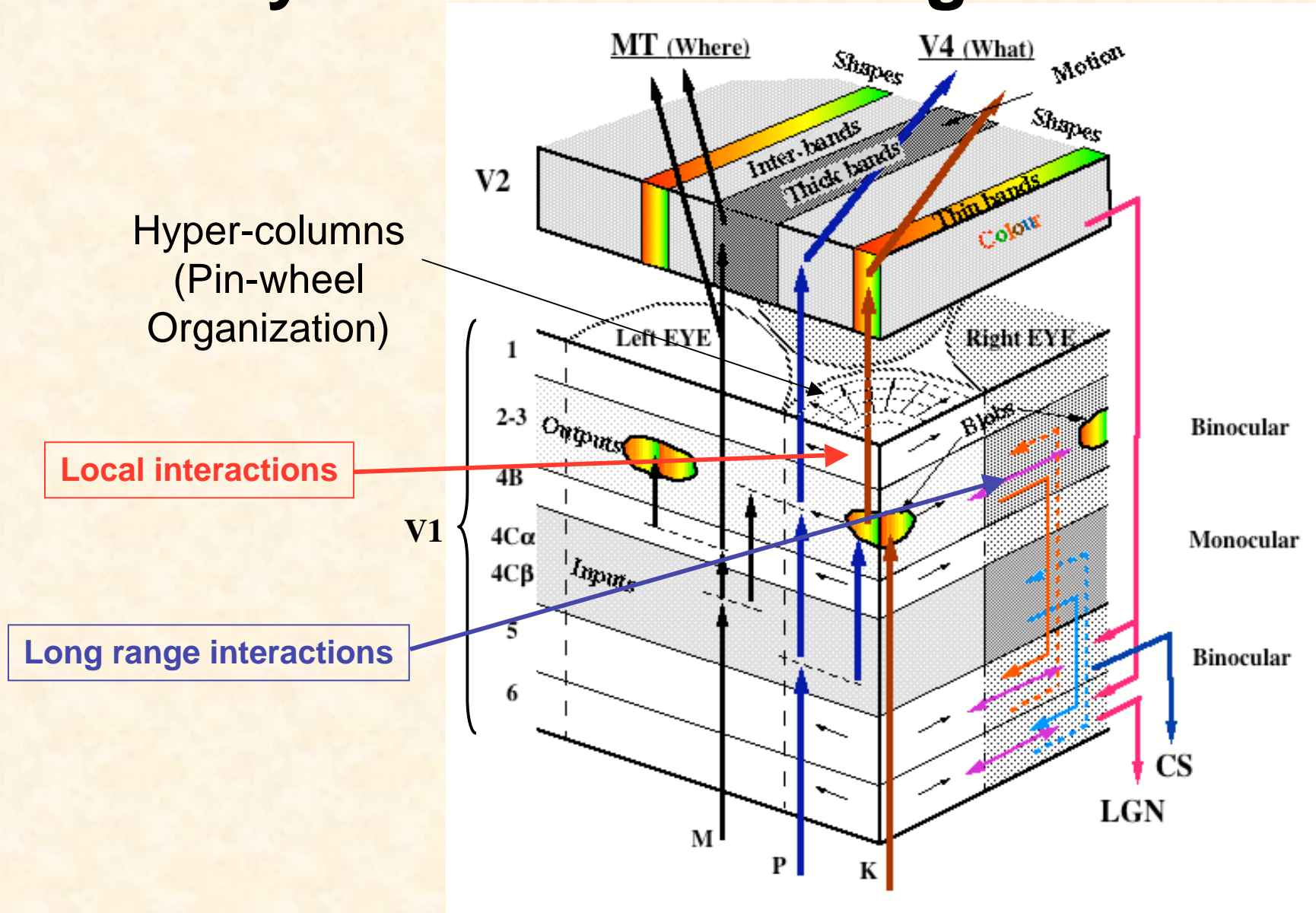
3. Color Constancy \Rightarrow at the photoreceptor level



Retino-Cortical Projections



Primary Visual Cortex: Organization



2nd Order Statistics and SPECTRAL ANALYSIS

Stat Autocorrelation: $R(x_1, y_1, x_2, y_2) = \mathbf{E}[i(x_1, y_1) \cdot i(x_2, y_2)]$ over all images, or by category

H1: Stationary process

$$R(x, y) = \mathbf{E}[i(x_1, y_1) \cdot i(x_1 - x, y_1 - y)]$$

Th. Wiener-Kinchine: $F\{R(x, y)\} = S(f_x, f_y) \implies$ Spectral Density of Energy

H2: Ergodicity:

$$R(x, y) = \gamma(x, y) = \iint_{x_1, y_1} i(x_1, y_1) \cdot i(x_1 - x, y_1 - y) dx_1 dy_1$$

Statistical Autocorrelation = Spatial Autocorrelation

Properties: $S(f_x, f_y) = F\{\gamma(x, y)\} = |F\{i(x, y)\}|^2$ *The amplitude of the frequency spectrum is independent of the image position*

\implies One image is considered as a particular sample of a stochastic process

$|F\{i(x, y)\}|^2 \Leftrightarrow S_C(f_x, f_y)$ *The amplitude spectrum of an image is similar to that of its category*

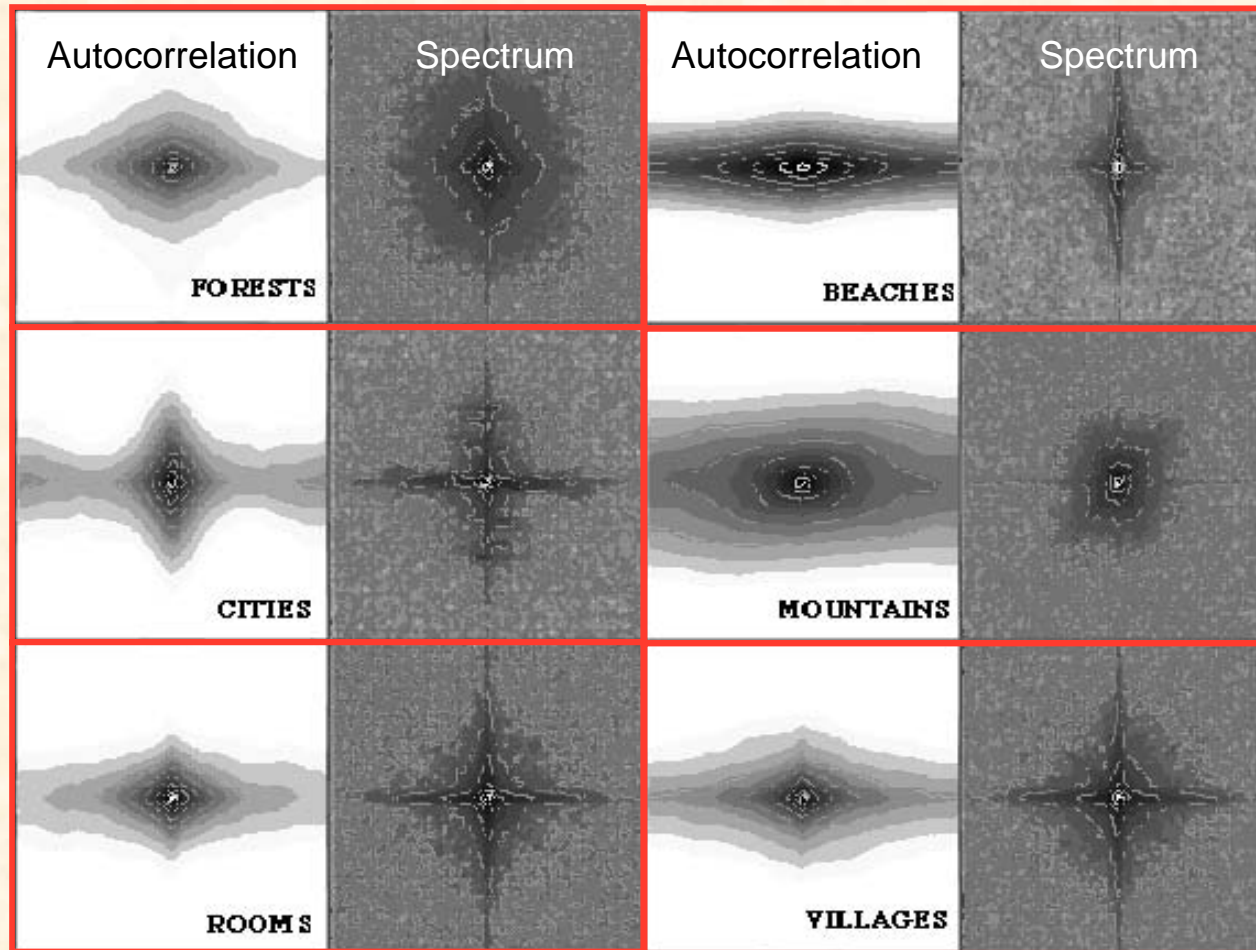
Frequency Spectra of Scenes

1. Image data base



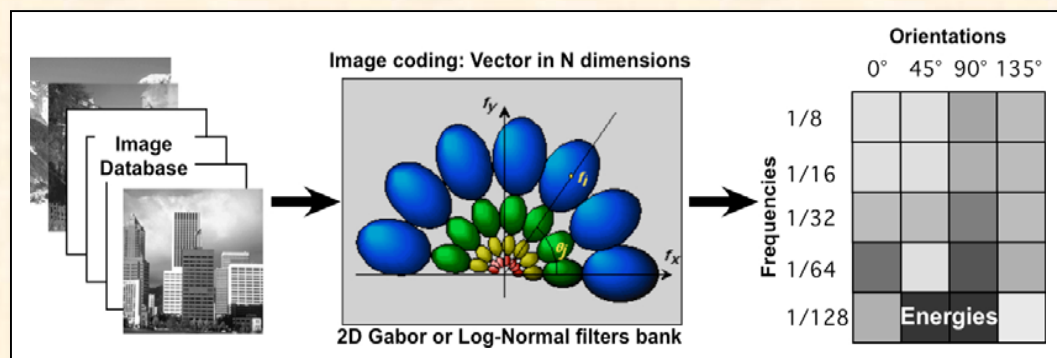
Frequency Spectra of Scenes

2. Mean Energy Spectra of image Categories



Cortical Model of Scene Analysis

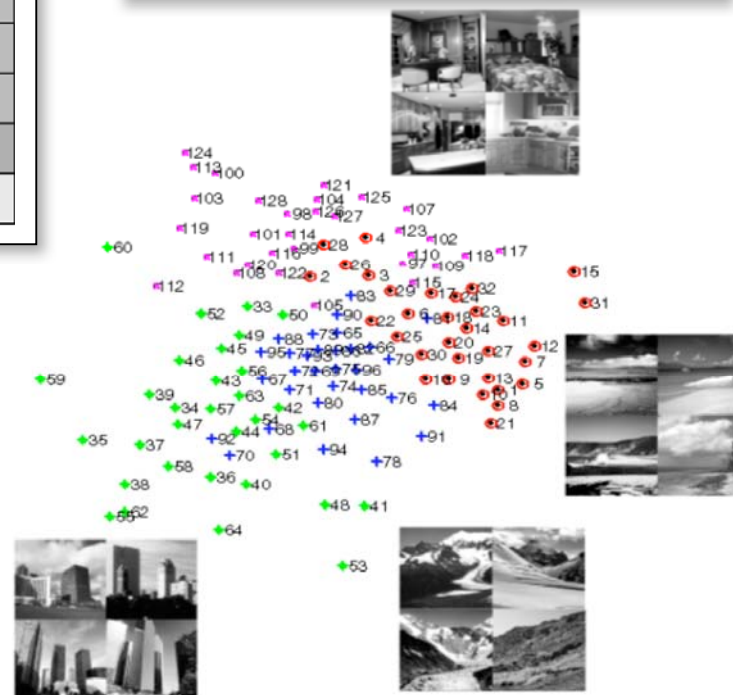
Image Coding



Pin wheel models of V1 Complex cells

1. the N-dimensional space is not fully spanned by the image vectors
2. the N dimensions are non-linearly correlated

Scene Categorization by CCA: (Non-linear MDS with Metrics & Manifolds considerations)



2D SPECTRAL ANALYSIS

2D image spectrum:

$$I(f_x, f_y) = \iint_{x,y} i(x, y) \exp[-j2\pi(x f_x + y f_y)] dx dy$$

==> Cartesian in frequency

$$I(f, \theta) = \iint_{x,y} i(x, y) \exp[-j2\pi f(x \cos(\theta) + y \sin(\theta))] dx dy$$

==> Polar in frequency

In Vector notation:

$$i(x, y) \xrightarrow{\mathbf{x}=[x,y]} i(\mathbf{x})$$

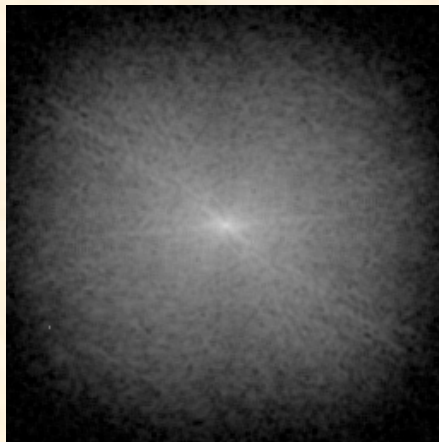
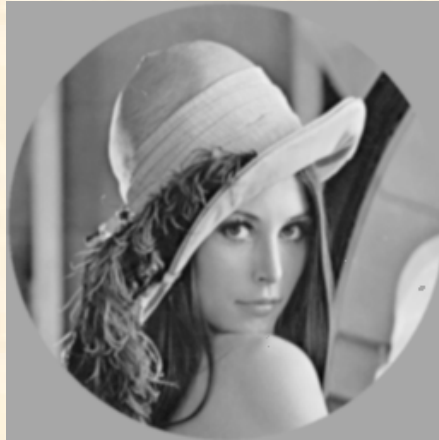
$$I(f_x, f_y) \xrightarrow{\mathbf{f}=\begin{matrix} [f_x, f_y] \\ \text{cartesian} \end{matrix} = f \begin{matrix} e^{j\theta} \\ \text{polar} \end{matrix}} I(\mathbf{f})$$

$$I(\mathbf{f}) = \iint_{\mathbf{x}} i(\mathbf{x}) \exp[-j2\pi(\mathbf{x}^T \mathbf{f})] d\mathbf{x}$$

Remark:

$$\gamma(\mathbf{x}) = i(\mathbf{x}) * i(-\mathbf{x}) \Rightarrow \gamma(\mathbf{x}) = \gamma(-\mathbf{x}) \Rightarrow S(\mathbf{f}) = S(-\mathbf{f}) \quad \Rightarrow S(\mathbf{f}) \text{ is } \pi \text{ periodic in } \theta$$

The Energy Spectrum is π Periodic



THIS TEXT CONTAINS
TRANSFORMATIONS
THAT AFFECT UNDERSTANDING



Variability within a same Category

spectrum of a 2D image transformation:

$$\mathcal{F}\{i(\mathbf{Ax})\} = \iint_{\mathbf{x}} i(\mathbf{Ax}) \exp[-j2\pi(\mathbf{x}^T \mathbf{f})] d\mathbf{x} \quad \xrightarrow{\mathbf{x}' = \mathbf{Ax}} \quad \mathcal{F}\{i(\mathbf{Ax})\} = \frac{1}{|\det(\mathbf{A})|} \iint_{\mathbf{x}'} i(\mathbf{x}') \exp\left[-j2\pi(\mathbf{x}'^T \underbrace{\mathbf{A}^{-T} \mathbf{f}}_{\mathbf{f}'})\right] d\mathbf{x}'$$

Mirror: $i(x, y) \rightarrow i(-x, y) \Rightarrow I(f_x, f_y) \rightarrow I(-f_x, f_y)$

Zoom:

$\mathbf{A} = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$

$\mathcal{F}\{i(a\mathbf{x})\} = \frac{1}{a^2} I\left(\frac{\mathbf{f}}{a}\right)$

Rotation:

$\mathbf{A} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} = \mathbf{R}_\theta$

$\mathcal{F}\{i(\mathbf{R}\mathbf{x})\} = I(\mathbf{R}\mathbf{f})$

+ Perspective...

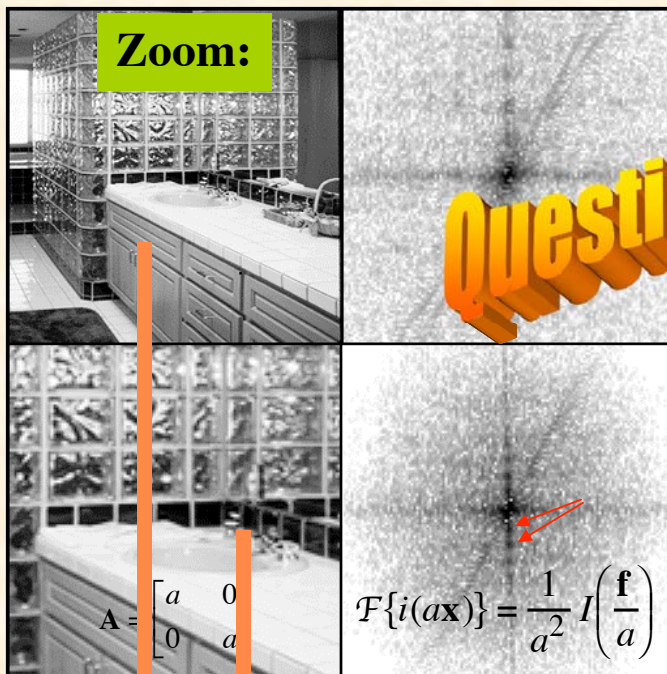
Variability within a same Category

spectrum of a 2D image transformation:

$$\mathcal{F}\{i(\mathbf{Ax})\} = \iint_{\mathbf{x}} i(\mathbf{Ax}) \exp[-j2\pi(\mathbf{x}^T \mathbf{f})] d\mathbf{x} \xrightarrow{\mathbf{x}' = \mathbf{Ax}} \mathcal{F}\{i(\mathbf{Ax})\} = \frac{1}{|\det(\mathbf{A})|} \iint_{\mathbf{x}'} i(\mathbf{x}') \exp\left[-j2\pi(\mathbf{x}'^T \underbrace{\mathbf{A}^{-T} \mathbf{f}}_{\mathbf{f}'})\right] d\mathbf{x}'$$

Mirror: $i(x, y) \rightarrow i(-x, y) \Rightarrow I(f_x, f_y) \rightarrow I(-f_x, f_y)$

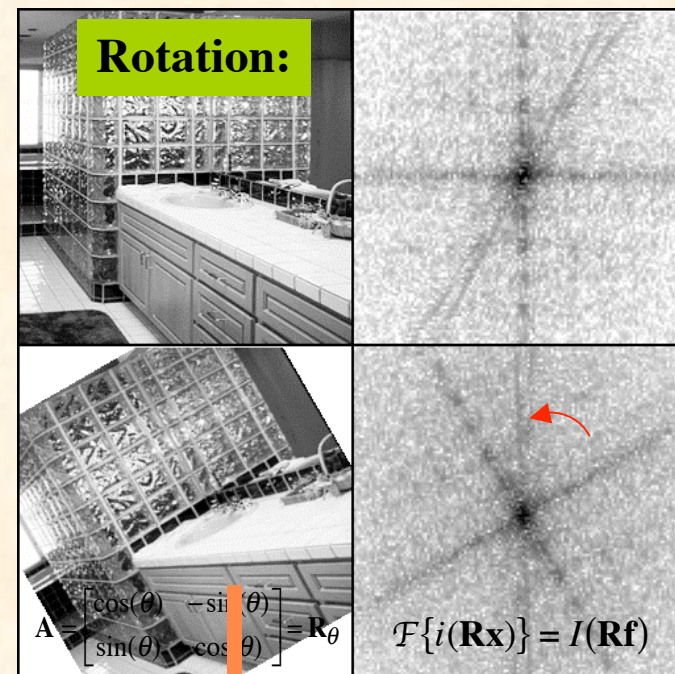
Zoom:



Question

$$\mathbf{A} = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix} \quad \mathcal{F}\{i(a\mathbf{x})\} = \frac{1}{a^2} I\left(\frac{\mathbf{f}}{a}\right)$$

Rotation:



$$\mathbf{A} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} = \mathbf{R}_\theta \quad \mathcal{F}\{i(\mathbf{R}\mathbf{x})\} = I(\mathbf{R}\mathbf{f})$$

Same category ?

+ Perspective...

LOG-POLAR REPRESENTATION

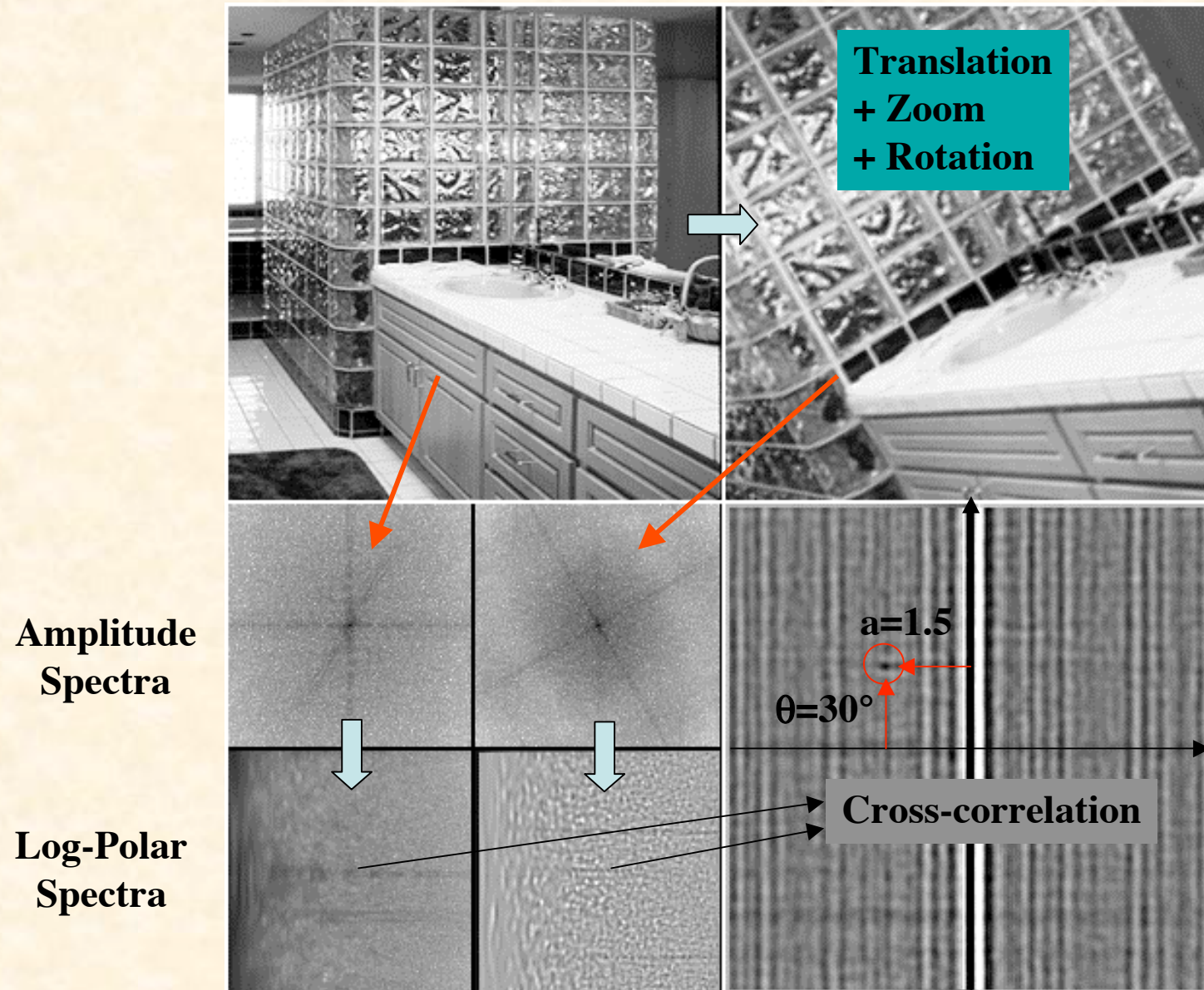
Use of the Log-Polar frequency spectrum:

$$\mathcal{F}\{i(a\mathbf{R}_\theta\mathbf{x})\} = \underbrace{\frac{1}{a^2} I\left(\frac{\mathbf{R}_\theta\mathbf{f}}{a}\right)}_{\text{Cartesian}} = \underbrace{\frac{1}{a^2} I(e^{v-\ln(a)}, \varphi - \theta)}_{\text{Log-polar}} \quad \text{if } v = \ln(f)$$

A zoom factor in the image space ==> a translation in log-frequency

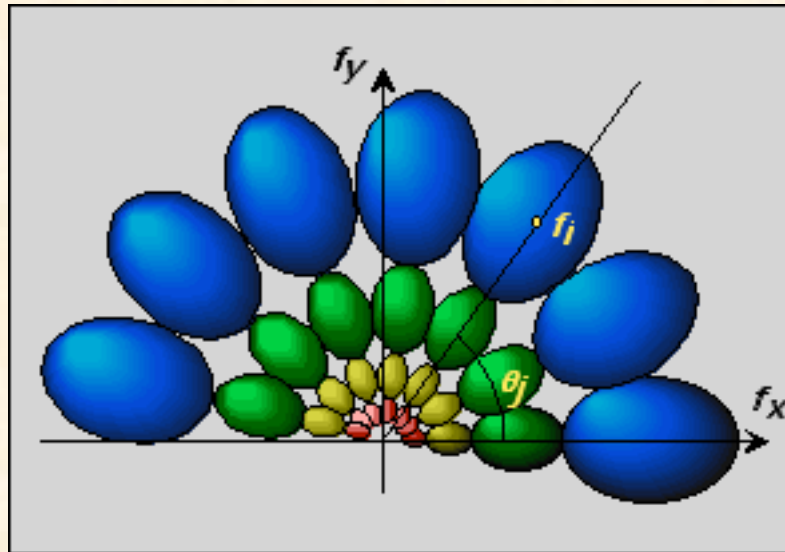
A rotation in the image space ==> a translation in angular frequency

INTEREST OF LOG-POLAR SPECTRA



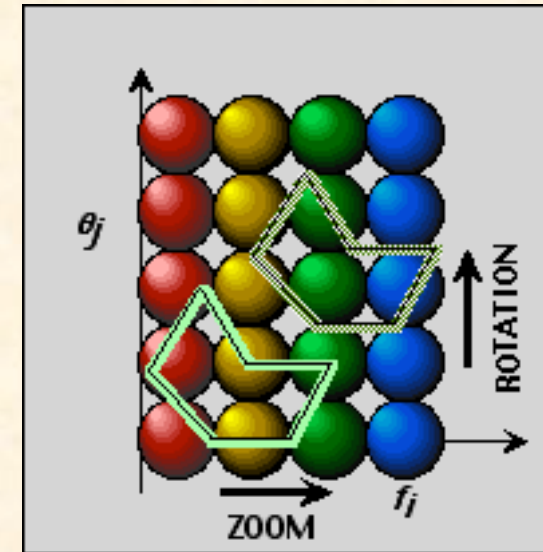
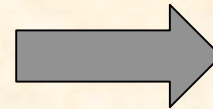
Properties OF LOG-POLAR FILTERS

2D Filter bank



$$f_{i+1} = k f_i, \quad \theta_{j+1} = \theta_j + \frac{k'}{\pi}$$

Log-Polar Transform



$$v_{i+1} = v_i + \ln(k), \quad \theta_{j+1} = \theta_j + \frac{k'}{\pi}$$

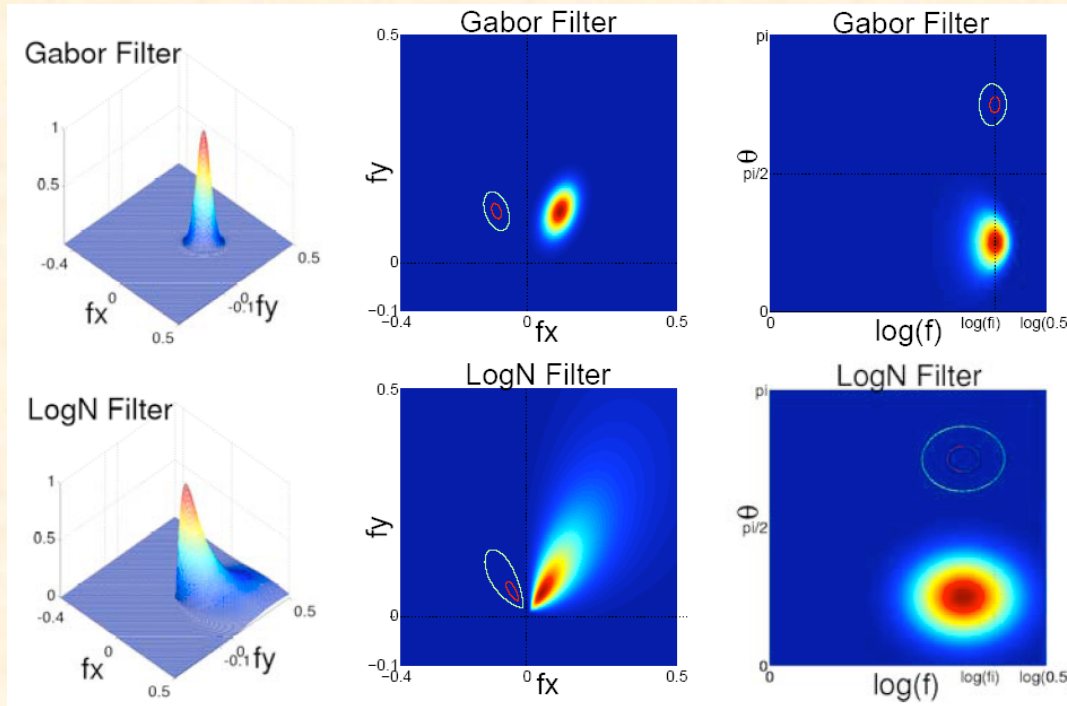
- Image **zoom** and **rotation** correspond both to log-polar **spectral translation**
- Image **perspective** corresponds to a log-polar **shear**

Two kinds of LOG-POLAR Filter banks

Gabor and Log-Normal filters

Gabor

$$G_i(f) = e^{-\frac{(f-f_i)^2}{2\sigma^2}}$$



Log-Normal

$$G_i(f) = \frac{1}{f} e^{-\frac{[\ln(f/f_i)]^2}{2\sigma^2}}$$

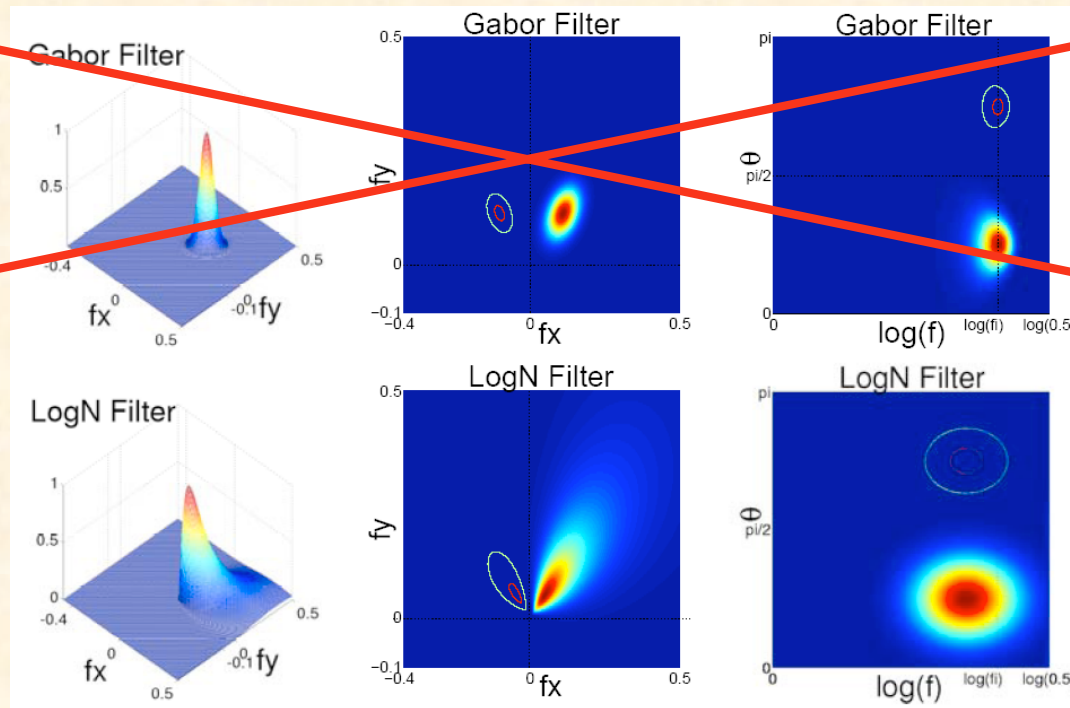
Gaussian filters in log-polar domain => log-normal filters in cartesian domain

Two kinds of LOG-POLAR Filter banks

Gabor and Log-Normal filters

Gabor

$$G_i(f) = e^{-\frac{(f-f_i)^2}{2\sigma^2}}$$



Log-Normal

$$G_i(f) = \frac{1}{f} e^{-\frac{[\ln(f/f_i)]^2}{2\sigma^2}}$$

=> Log-normal filters are more suitable and more biologically plausible than classical Gabor filters

Properties OF LOG-NORMAL FILTERS

2D filters with separable radial and angular variables:

$$|G_{ij}|^2 = |G_i|^2 |G_j|^2$$

Mean energy in each frequency band :

$$C_{ij} = \iint_{f,\theta} S(f,\theta) \left[\frac{1}{f^2} e^{-\frac{\ln^2(f/f_i)}{2\sigma^2}} \right] \left[(\cos(\theta - \theta_j))^{2n} \right] f df d\theta$$

G_i are Log-normal filters:

$$|G_i| = \frac{1}{f} e^{-\frac{(\ln(f/f_i))^2}{4\sigma^2}}$$

G_j are π periodic Gaussian-like filters:

$$|G_j| = (\cos(\theta - \theta_j))^{2n}$$

with: $v = \ln(f / f_0)$

$$C_{ij} = \iint_{v,\theta} S(e^v, \theta) e^{-\frac{(v-v_i)^2}{2\sigma^2}} (\cos(\theta - \theta_j))^{2n} dv d\theta$$

For zoom and rotation:

$$i(a \mathbf{R}_\varphi \mathbf{x}) \Leftrightarrow \frac{1}{a^2} I\left(\frac{1}{a} \mathbf{R}_\varphi \mathbf{f}\right)$$



$$C_{ij} \approx \frac{1}{a^4} \iint_{v,\theta} \left[S(e^{v-\ln(a)}, \theta - \varphi) \right] e^{-\frac{(v-v_i)^2}{2\sigma^2}} e^{-\frac{(\theta-\theta_j)^2}{2\sigma^2}} dv d\theta$$

$$C_{ij} \approx \frac{1}{a^4} \iint_{v,\theta} S(e^v, \theta) \left[e^{-\frac{(v-v_i+\ln(a))^2}{2\sigma^2}} e^{-\frac{(\theta-\theta_j+\varphi)^2}{2\sigma^2}} \right] dv d\theta$$

==> *The log-polar spectrum is regularly sampled by the filter bank in f_i and θ_j
If the number of filters is odd, non-integer translations in f_i and θ_j can be coded*

INTEREST OF LOG-NORMAL FILTERS (1)

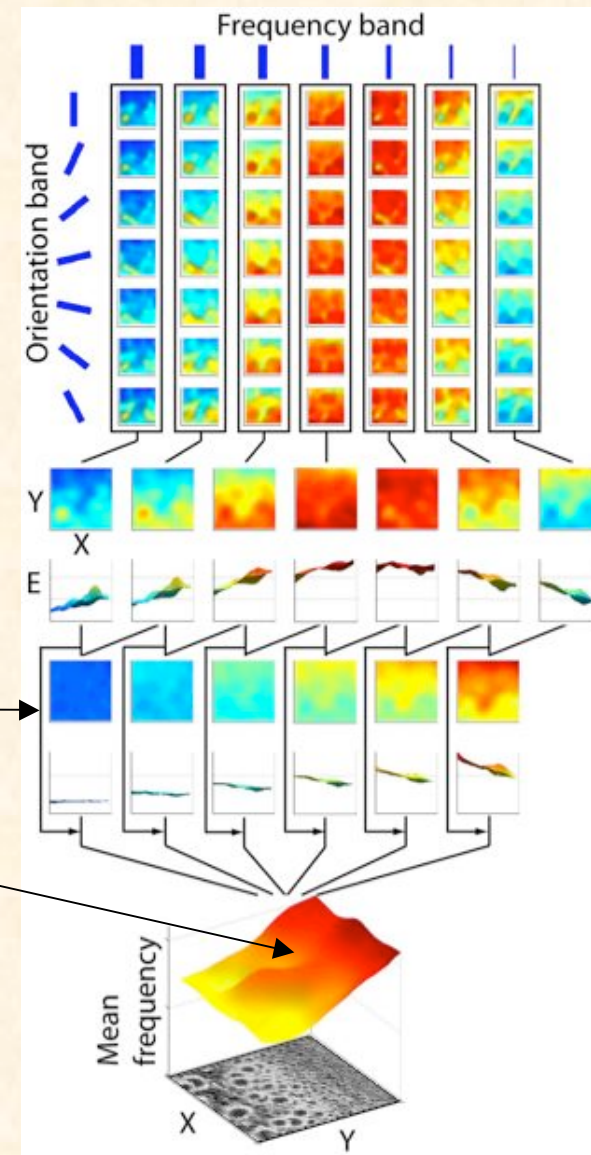
Perspective estimation through
local frequency gradient

*(similar to long-range
inretactions in V1)*

narrow-band local frequency

$$\frac{C_{i+1}(x, y)}{C_i(x, y)} = \frac{1}{\sqrt{f_i f_{i+1}}} \langle f \rangle_i(x, y)$$

wide-band local frequency



INTEREST OF LOG-NORMAL FILTERS (2)

Fourier transform of C_{ij}

$$\mathcal{F}\{C_{ij}\} = \frac{1}{a^4} \iint_{v_i, \theta_i} \iint_{v, \theta} S(e^v, \theta) e^{-\frac{(v-v_i+\ln(a))^2}{2\sigma^2}} e^{-\frac{(\theta-\theta_j+\varphi)^2}{2\sigma^2}} dv d\theta e^{-j2\pi(\xi v_i + \eta \theta_j)} dv_j d\theta_j$$

$$\mathcal{F}\{C_{ij}\}(\xi, \eta) = \frac{1}{a^4} e^{-(k_1 \xi^2 + k_2 \eta^2)} e^{-j2\pi(\xi \ln(a) + \eta \varphi)} \iint_{v, \theta} S(e^v, \theta) e^{-j2\pi(\xi v + \eta \theta)} dv d\theta$$

Gaussian envelope

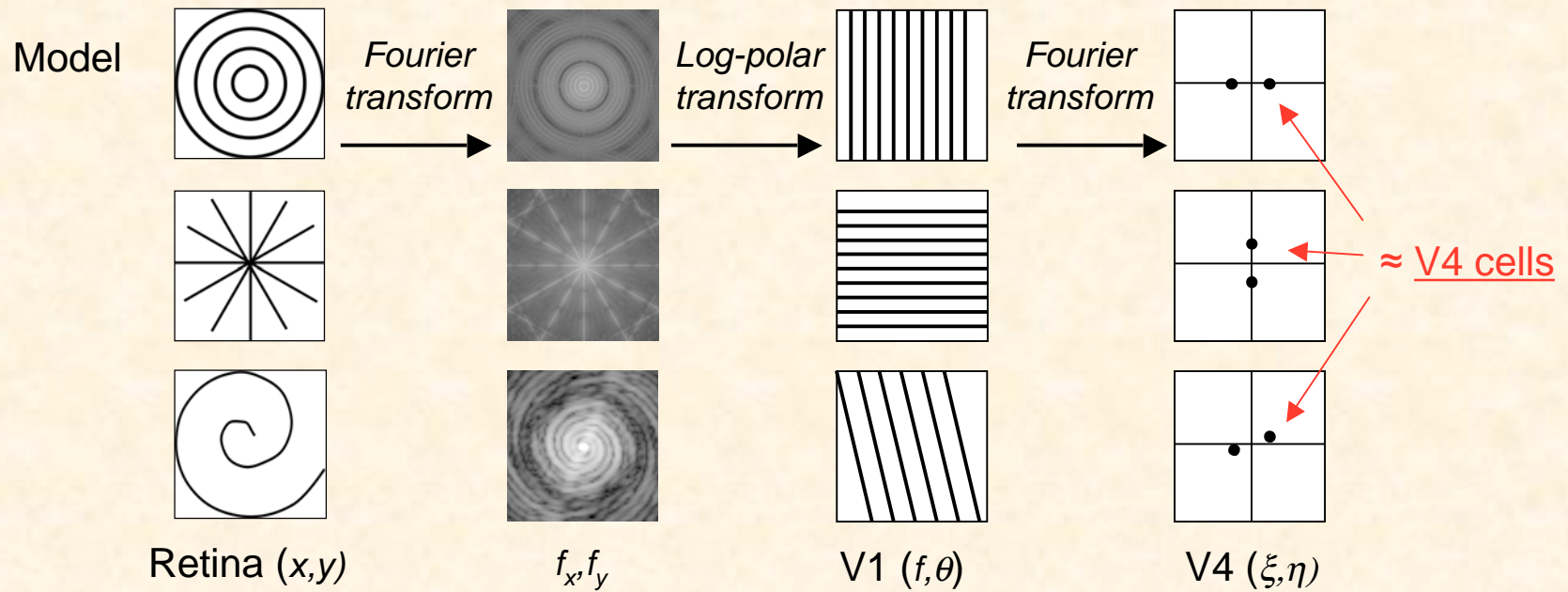
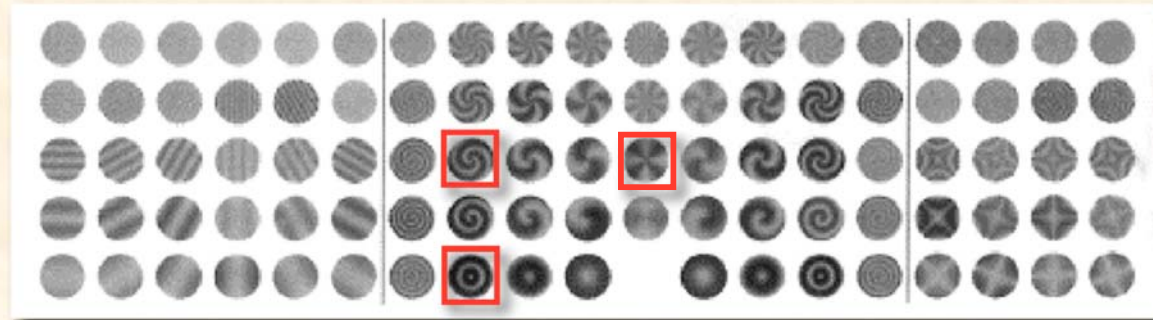
Zoom & Rotation

$$|\mathcal{F}\{C_{ij}\}(\xi, \eta)| \text{ independent of } (a, \varphi)$$

==> a possible operation done in visual area V4...

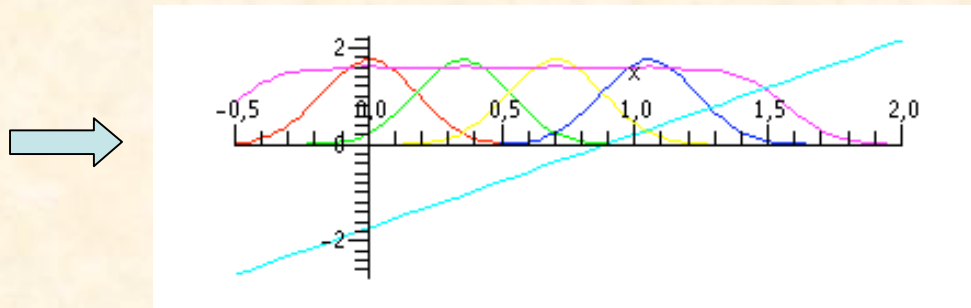
Model of V4

Stimuli and Best responses in area V4 cells



CHOOSING BANDWIDTHS

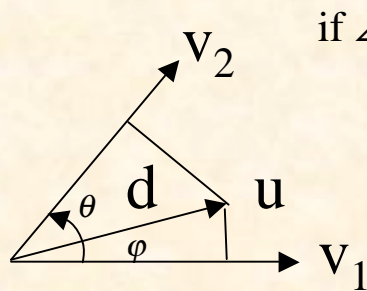
The log-spectrum is convolved by: $e^{-\frac{(\ln(f/f_i))^2}{2\sigma^2}}$ Then sampled every $\Delta\nu = \ln(f_{i+1}/f_i)$



σ is chosen according to Nyquist condition
or spectral coverage

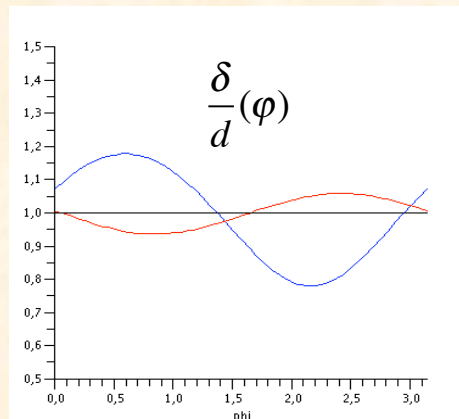
Pb: ORTHOGONALITY of FILTERS

$$C_{ij} = \frac{1}{a^4} \iint_{v,\theta} S(e^v, \theta) e^{-\frac{(v-v_i)^2}{2\sigma^2}} e^{-\frac{(\theta-\theta_j)^2}{2\sigma^2}} dv d\theta = \text{dot product between a signal } S(e^v, \theta) \text{ and functions } \mathbf{v}_{ij} = |G_{ij}|^2$$



if $\angle \mathbf{v}_i \mathbf{v}_j = \theta \neq 90^\circ$, the estimated "Euclidean" distance δ is not the real one d :

$$\delta^2 = d^2 \cos^2(\varphi) + d^2 \cos^2(\theta - \varphi)$$



example for various θ : $\angle C_1 C_2 = 67^\circ$, $\angle C_1 C_3 = 88.7^\circ$, $\angle C_1 C_4 = 89.98^\circ$

ORTHOGONALITY of FILTERS (2)

Possible solution: **linear combinations of filters**

$$C_i \rightarrow \frac{C_i - aC_{i-1} - aC_{i+1}}{1+2a} \quad C_j \rightarrow \frac{C_j - a'C_{j-1} - a'C_{j+1}}{1+2a'}$$

a	$\angle C_1 C_2$	$\angle C_1 C_3$	$\angle C_1 C_4$
0.18	85.75	96.07	89.66
0.21	89.21	97.09	89.42
0.23	91.54	97.71	89.21

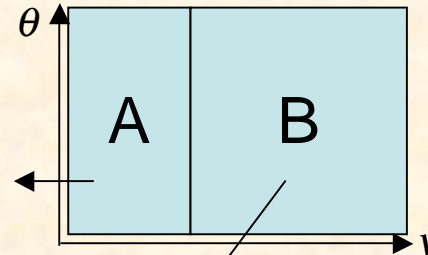
$$a \approx 0.2$$

similar to cortical interactions between filters \implies Euclidean distances are better approximated

Problem with different Zoom Ratios

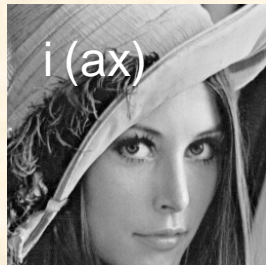


$I_1(\ln(f)) \Rightarrow$

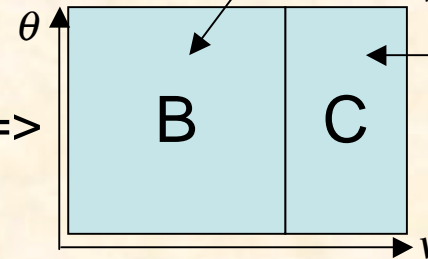


Low frequencies (A) disappear

Frequency pattern (B) translates



$I_2(\ln(f)-\ln(a)) \Rightarrow$



High frequencies (C) appear

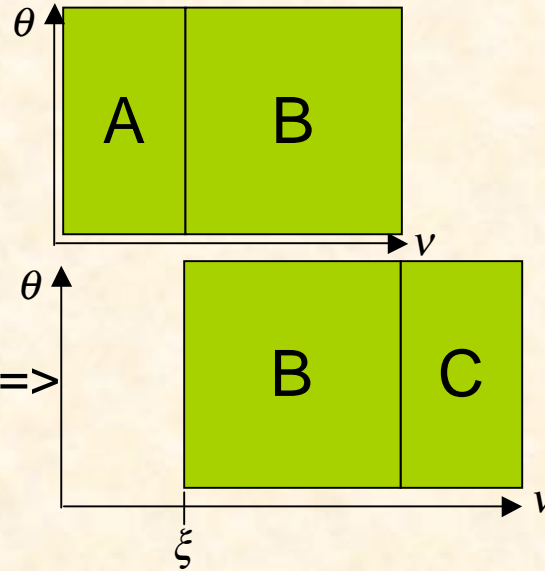
Classical distance: $d_{1,2}^2 = \|I_1\|^2 + \|I_2\|^2 - \gamma_{1,2}(0) - \gamma_{2,1}(0) = \|A\|^2 + 2\|B\|^2 + \|C\|^2 - \gamma_{1,2}(0) - \gamma_{2,1}(0)$

should disappear

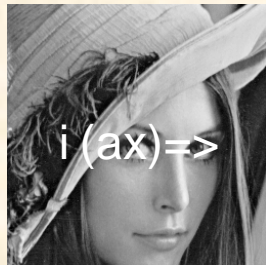
Problem with different Zoom Ratios



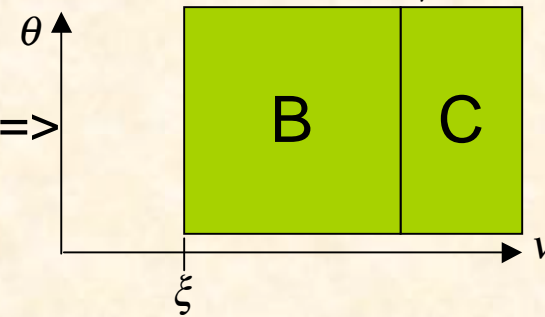
$$I_1(\ln(f)) \Rightarrow$$



search for maximum intercorrelation



$$I_2(\ln(f) - \ln(a)) \Rightarrow$$

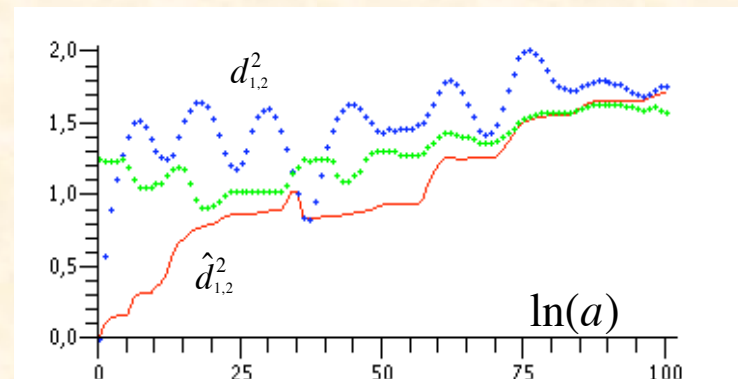


Better distance would be:

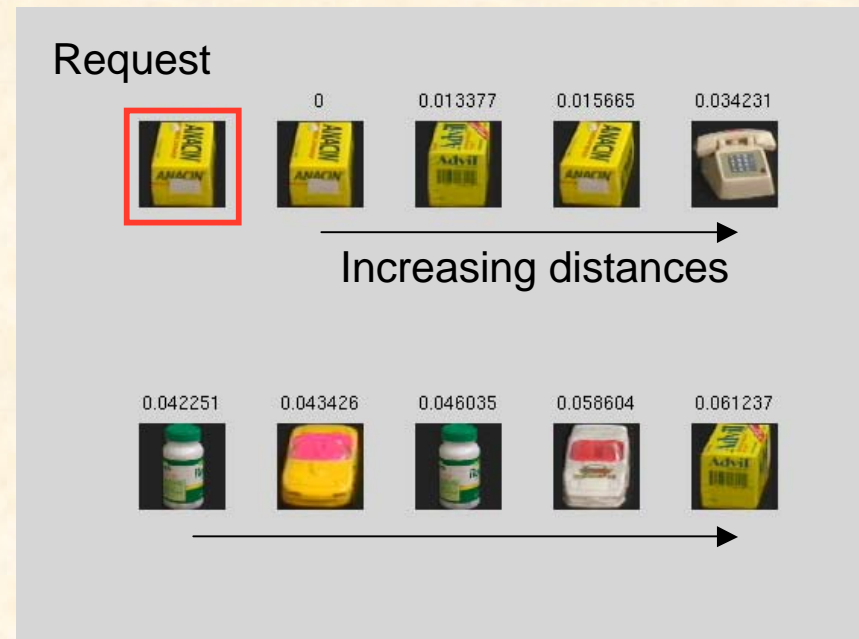
$$\hat{d}_{1,2}^2 = \|A\|^2 + \|C\|^2$$

That is:

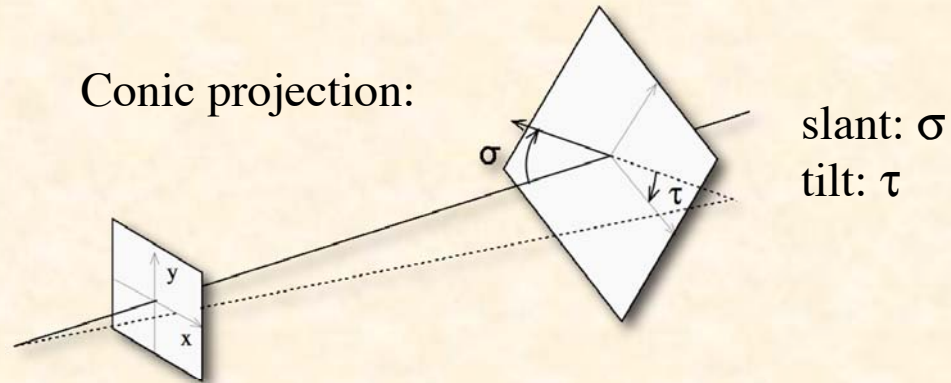
$$\hat{d}_{1,2}^2 = \underbrace{\|I_1\|^2 + \|I_2\|^2}_{\|A\|^2 + 2\|B\|^2 + \|C\|^2} - 2 \underbrace{\text{Max}(\gamma_{1,2}(\xi))}_{2\|B\|^2}$$



EXAMPLES

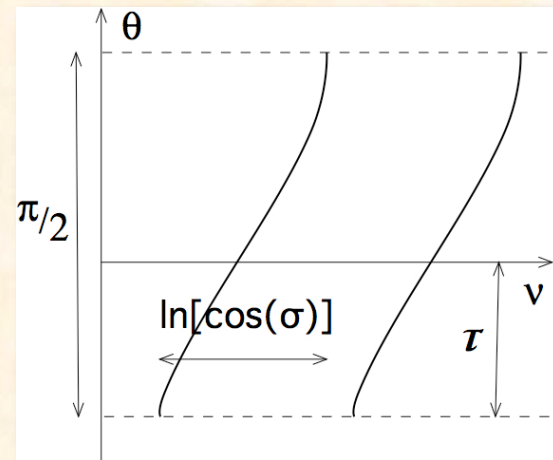


For PERSPECTIVE



*Maximum frequency expansion: $\ln[\cos(\sigma)]$
at $\theta = \pi/2 + \tau$*

Log-polar frequency plane



To be continued...

**Thank you for
your attention**